

- High resolution module, 10 cm
- Fast conversion down to 1 ms
- Low power, 1  $\mu$ A (standby < 0.15  $\mu$ A)
- QFN package 5.0 x 3.0 x 1.0 mm<sup>3</sup>
- Supply voltage 1.8 to 3.6 V
- Integrated digital pressure sensor (24 bit ΔΣ ADC)
- Operating range: 10 to 1200 mbar, -40 to +85 ℃
- I<sup>2</sup>C and SPI interface up to 20 MHz
- No external components (Internal oscillator)
- Excellent long term stability

### DESCRIPTION

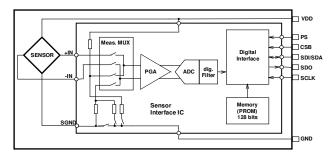
The MS5611-01BA is a new generation of high resolution altimeter sensors from MEAS Switzerland with SPI and I<sup>2</sup>C bus interface. It is optimized for altimeters and variometers with an altitude resolution of 10 cm. The sensor module includes a high linearity pressure sensor and an ultra low power 24 bit  $\Delta\Sigma$  ADC with internal factory calibrated coefficients. It provides a precise digital 24 Bit pressure and temperature value and different operation modes that allow the user to optimize for conversion speed and current consumption. A high resolution temperature output allows the implementation of an altimeter/thermometer function without any additional sensor. The MS5611-01BA can be interfaced to virtually any microcontroller. The communication protocol is simple, without the need of programming internal registers in the device. Small dimensions of only 5.0 mm x 3.0 mm and a height of only 1.0 mm allow for integration in mobile devices. This new sensor module generation is based on leading MEMS technology and latest benefits from MEAS Switzerland proven experience and know-how in high volume manufacturing of altimeter modules, which have been widely used for over a decade. The sensing principle employed leads to very low hysteresis and high stability of both pressure and temperature signal.

### **FEATURES**

### FIELD OF APPLICATION

- Mobile altimeter / barometer systems
- Bike computers
- Variometers
- Height sensing for medical alarms
- Indoor navigation

### FUNCTIONAL BLOCK DIAGRAM



### **TECHNICAL DATA**

Sensor Performances (VDD	o = 3 V)	)		
Pressure	Min	Тур	Мах	Unit
Range	10		1200	mbar
ADC		24		bit
Resolution (1)	0.065 / 0	mbar		
Accuracy 25 ℃, 750 mbar	-1.5		+1.5	mbar
Error band, -20 °C to +85 °C 450 to 1100 mbar (2)	· -2.5 +2.5			mbar
Response time (1)	0.5 /	1.1 / 2.1 8.22	/ 4.1 /	ms
Long term stability		-1		mbar/yr
Temperature	Min	Тур	Max	Unit
Range	-40		+85	°C
Resolution		<0.01		°C
Accuracy	-0.8		+0.8	°C
Notes: (1) Oversampling Ratio: (2) With autozero at one			2048 / 4	4096

## PERFORMANCE SPECIFICATIONS

### ABSOLUTE MAXIMUM RATINGS

Parameter	Symbol	Conditions	Min.	Тур.	Max	Unit
Supply voltage	V <sub>DD</sub>		-0.3		+4.0	V
Storage temperature	Ts		-40		+125	°C
Overpressure	P <sub>max</sub>				6	bar
Maximum Soldering Temperature	T <sub>max</sub>	40 sec max			250	°C
ESD rating		Human Body Model	-4		+4	kV
Latch up		JEDEC standard No 78	-100		+100	mA

### **ELECTRICAL CHARACTERISTICS**

Parameter	Symbol	Conditions	Min.	Тур.	Max	Unit
Operating Supply voltage	V <sub>DD</sub>		1.8	3.0	3.6	V
Operating Temperature	Т		-40	+25	+85	°C
		OSR 4096		12.5		
Supply current		2048		6.3		
	I <sub>DD</sub>	1024		3.2		μA
(1 sample per sec.)		512		1.7		
		256		0.9		
Peak supply current		during conversion		1.4		mA
Standby supply current		at 25 <i>°</i> C		0.02	0.14	μA
VDD Capacitor		From VDD to GND	100			nF

### ANALOG DIGITAL CONVERTER (ADC)

Parameter	Symbol	Conditions		Min.	Тур.	Мах	Unit
Output Word					24		bit
		OSR	4096	7.40	8.22	9.04	
			2048	3.72	4.13	4.54	
Conversion time	t <sub>c</sub>		1024	1.88	2.08	2.28	ms
			512	0.95	1.06	1.17	
			256	0.48	0.54	0.60	

## **PERFORMANCE SPECIFICATIONS (CONTINUED)**

### PRESSURE OUTPUT CHARACTERISTICS (V<sub>DD</sub> = 3 V, T = 25 °C UNLESS OTHERWISE NOTED)

Parameter	Conditio	ons	Min.	Тур.	Max	Unit
Operating Pressure Range	Prange	Full Accuracy	450		1100	mbar
Extended Pressure Range	P <sub>ext</sub>	Linear Range of ADC	10		1200	mbar
	at 25℃,	at 25℃, 7001100 mbar			+1.5	
Total Error Dand, no outozoro	at 050°	at 050℃, 4501100 mbar			+2.0	mbor
Total Error Band, no autozero	at -208	at -2085℃, 4501100 mbar			+3.5	mbar
	at -4085℃, 4501100 mbar		-6.0		+6.0	
	at 25℃,	at 25 ℃, 7001100 mbar			+0.5	
Total Error Band, autozero at one pressure point	at 1050	)℃, 4501100 mbar	-1.0		+1.0	mbar
	at -2085°C, 4501100 mbar		-2.5		+2.5	mbar
	at -4085℃, 4501100 mbar		-5.0		+5.0	
Maximum error with supply voltage	V <sub>DD</sub> = 1.	8 V 3.6 V	-2.5		+2.5	mbar
Long-term stability				-1		mbar/yr
Recovering time after reflow (1)				7		days
	OSR	4096		0.012		
		2048		0.018		
Resolution RMS	1024			0.027		mbar
		512		0.042		
		256		0.065		

(1) Time to recovering at least 66% of the reflow impact

### TEMPERATURE OUTPUT CHARACTERISTICS (V<sub>DD</sub> = 3 V, T = 25 °C UNLESS OTHERWISE NOTED)

Parameter	Conditions		Min.	Тур.	Max	Unit
	at 25 <i>°</i> C		-0.8		+0.8	
Absolute Accuracy	-2085 <i>°</i> C		-2.0		+2.0	°C
	-4085℃		-4.0		+4.0	
Maximum error with supply voltage	$V_{DD} = 1.8 V \dots 3.6 V$		-0.5		+0.5	°C
	OSR	4096		0.002		
		2048		0.003		
Resolution RMS		1024		0.005		°C
		512		0.008		
		256		0.012		

## **PERFORMANCE SPECIFICATIONS (CONTINUED)**

## DIGITAL INPUTS (CSB, I<sup>2</sup>C, DIN, SCLK)

Parameter	Symbol	Conditions	Min.	Тур.	Max	Unit
Serial data clock	SCLK	SPI protocol			20	MHz
Input high voltage	VIH	Pins CSB	80% V <sub>DD</sub>		100% V <sub>DD</sub>	V
Input low voltage	VIL		0% V <sub>DD</sub>		$20\% V_{DD}$	V
Input leakage current	I <sub>leak25℃</sub> I <sub>leak85℃</sub>	at 25℃			0.15	μΑ

## PRESSURE OUTPUTS (I<sup>2</sup>C, DOUT)

Parameter	Symbol	Conditions	Min.	Тур.	Max	Unit
Output high voltage	V <sub>OH</sub>	I <sub>source</sub> = 1.0 mA	$80\% V_{DD}$		$100\% V_{DD}$	V
Output low voltage	V <sub>OL</sub>	I <sub>sink</sub> = 1.0 mA	0% V <sub>DD</sub>		20% V <sub>DD</sub>	V
Load capacitance	$C_{LOAD}$				16	рF

## FUNCTIONAL DESCRIPTION

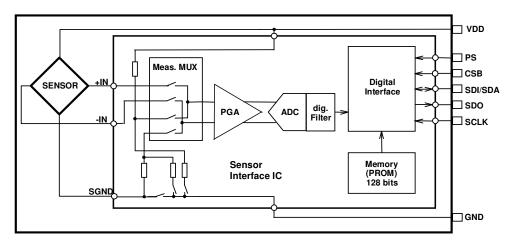


Figure 1: Block diagram of MS5611-01BA

### GENERAL

The MS5611-01BA consists of a piezo-resistive sensor and a sensor interface IC. The main function of the MS5611-01BA is to convert the uncompensated analogue output voltage from the piezo-resistive pressure sensor to a 24-bit digital value, as well as providing a 24-bit digital value for the temperature of the sensor.

### FACTORY CALIBRATION

Every module is individually factory calibrated at two temperatures and two pressures. As a result, 6 coefficients necessary to compensate for process variations and temperature variations are calculated and stored in the 128-bit PROM of each module. These bits (partitioned into 6 coefficients) must be read by the microcontroller software and used in the program converting D1 and D2 into compensated pressure and temperature values.

### SERIAL INTERFACE

The MS5611-01BA has built in two types of serial interfaces: SPI and I<sup>2</sup>C. Pulling the Protocol Select pin PS to low selects the SPI protocol, pulling PS to high activates the I<sup>2</sup>C bus protocol.

Pin PS	Mode	Pins used
High	I <sup>2</sup> C	SDA
Low	SPI	SDI, SDO, CSB

### **SPI MODE**

The external microcontroller clocks in the data through the input SCLK (Serial CLocK) and SDI (Serial Data In). In the SPI mode module can accept both mode 0 and mode 3 for the clock polarity and phase. The sensor responds on the output SDO (Serial Data Out). The pin CSB (Chip Select) is used to enable/disable the interface, so that other devices can talk on the same SPI bus. The CSB pin can be pulled high after the command is sent or after the end of the command execution (for example end of conversion). The best noise performance from the module is obtained when the SPI bus is idle and without communication to other devices during the ADC conversion.

### I<sup>2</sup>C MODE

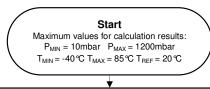
The external microcontroller clocks in the data through the input SCLK (Serial CLocK) and SDA (Serial DAta). The sensor responds on the same pin SDA which is bidirectional for the  $l^2C$  bus interface. So this interface type uses only 2 signal lines and does not require a chip select, which can be favorable to reduce board space. In  $l^2C$ -Mode the complement of the pin CSB (Chip Select) represents the LSB of the  $l^2C$  address. It is possible to use two sensors with two different addresses on the  $l^2C$  bus. The pin CSB shall be connected to VDD or GND (do not leave unconnected!).

### COMMANDS

The MS5611-01BA has only five basic commands:

- 1. Reset
- 2. Read PROM (128 bit of calibration words)
- 3. D1 conversion
- 4. D2 conversion
- 5. Read ADC result (24 bit pressure / temperature)

### PRESSURE AND TEMPERATURE CALCULATION



Read calibration data (factory calibrated) from PROM

Variable	Description   Equation	Recommended	Size <sup>[1]</sup>	Va	ue	Example / Typical
variable	Description   Equation	variable type	[bit]	min	max	
C1	Pressure sensitivity   SENS <sub>T1</sub>	unsigned int 16	16	0	65535	40127
C2	Pressure offset   OFF <sub>T1</sub>	unsigned int 16	16	0	65535	36924
С3	Temperature coefficient of pressure sensitivity   TCS	unsigned int 16	16	0	65535	23317
C4	Temperature coefficient of pressure offset   TCO	unsigned int 16	16	0	65535	23282
C5	Reference temperature   T <sub>REF</sub>	unsigned int 16	16	0	65535	33464
C6	Temperature coefficient of the temperature   TEMPSENS	unsigned int 16	16	0	65535	28312

Read digital pressure and temperature data							
D1	Digital pressure value	unsigned int 32	24	0	16777216	9085466	
D2	Digital temperature value	unsigned int 32	24	0	16777216	8569150	

•∢

	Calcu	late temperature	•			
dT	Difference between actual and reference temperature $^{[2]}$ dT = D2 - T <sub>REF</sub> = D2 - C5 * 2 <sup>8</sup>	signed int 32	25	-16776960	16777216	2366
TEMP	Actual temperature (-4085 °C with 0.01 °C resolution) $TEMP = 20$ °C + dT * TEMPSENS = $2000 + dT$ * $C6 / 2^{23}$	signed int 32	41	-4000	8500	2007 = 20.07 ℃

Calculate temperature compensated pressure									
OFF	Offset at actual temperature <sup>[3]</sup> $OFF = OFF_{T1} + TCO^* dT = C2^* 2^{16} + (C4^* dT) / 2^7$	signed int 64	41	-8589672450	12884705280	2420281617			
SENS	Sensitivity at actual temperature <sup>[4]</sup> SENS = SENS <sub>T1</sub> + TCS * dT = $C1 * 2^{15} + (C3 * dT)/2^8$	signed int 64	41	-4294836225	6442352640	1315097036			
Ρ	Temperature compensated pressure (101200mbar with 0.01mbar resolution) $P = D1 * SENS - OFF = (D1 * SENS / 2^{21} - OFF) / 2^{15}$	signed int 32	58	1000	120000	100009 = 1000.09 mbar			

### Display pressure and temperature value

Notes [1] [2] [3] [4]

- Maximal size of intermediate result during evaluation of variable
- min and max have to be defined min and max have to be defined
- min and max have to be defined min and max have to be defined

Figure 2: Flow chart for pressure and temperature reading and software compensation.

### SECOND ORDER TEMPERATURE COMPENSATION

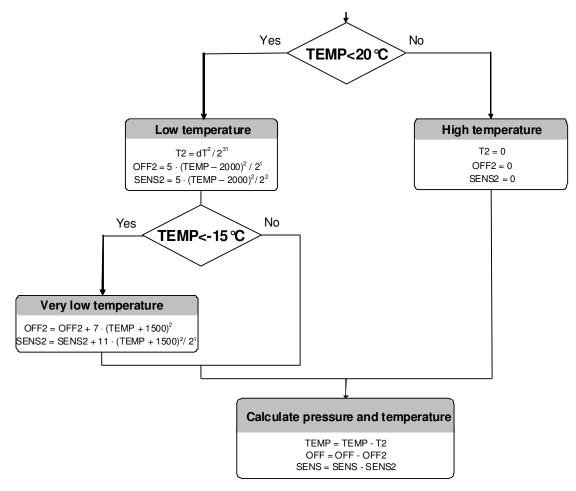


Figure 3: Flow chart for pressure and temperature to the optimum accuracy.

## **SPI INTERFACE**

### COMMANDS

Size of each command is 1 byte (8 bits) as described in the table below. After ADC read commands the device will return 24 bit result and after the PROM read 16bit result. The address of the PROM is embedded inside of the PROM read command using the a2, a1 and a0 bits.

	Com	mand I	byte						hex value
Bit number	0	1	2	3	4	5	6	7	
Bit name	PR M	COV	-	Тур	Ad2/ Os2	Ad1/ Os1	Ad0/ Os0	Stop	
Command									
Reset	0	0	0	1	1	1	1	0	0x1E
Convert D1 (OSR=256)	0	1	0	0	0	0	0	0	0x40
Convert D1 (OSR=512)	0	1	0	0	0	0	1	0	0x42
Convert D1 (OSR=1024)	0	1	0	0	0	1	0	0	0x44
Convert D1 (OSR=2048)	0	1	0	0	0	1	1	0	0x46
Convert D1 (OSR=4096)	0	1	0	0	1	0	0	0	0x48
Convert D2 (OSR=256)	0	1	0	1	0	0	0	0	0x50
Convert D2 (OSR=512)	0	1	0	1	0	0	1	0	0x52
Convert D2 (OSR=1024)	0	1	0	1	0	1	0	0	0x54
Convert D2 (OSR=2048)	0	1	0	1	0	1	1	0	0x56
Convert D2 (OSR=4096)	0	1	0	1	1	0	0	0	0x58
ADC Read	0	0	0	0	0	0	0	0	0x00
PROM Read	1	0	1	0	Ad2	Ad1	Ad0	0	0xA0 to 0xAE

Figure 4: Command structure

### **RESET SEQUENCE**

The Reset sequence shall be sent once after power-on to make sure that the calibration PROM gets loaded into the internal register. It can be also used to reset the device ROM from an unknown condition

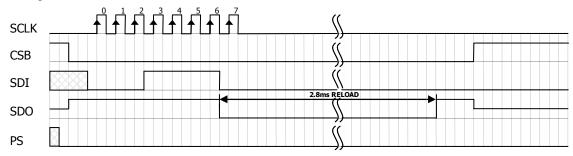
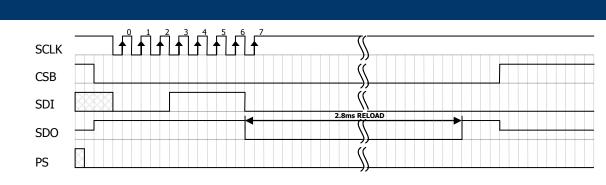
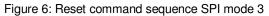


Figure 5: Reset command sequence SPI mode 0

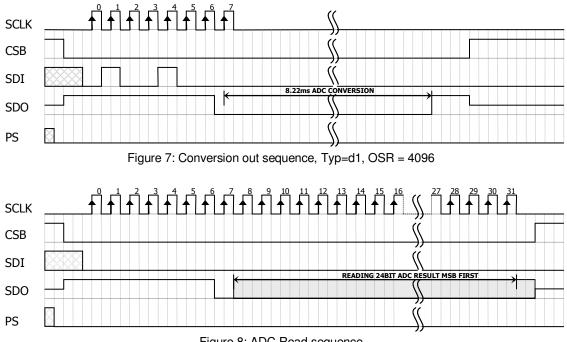




### **CONVERSION SEQUENCE**

The conversion command is used to initiate uncompensated pressure (D1) or uncompensated temperature (D2) conversion. The chip select can be disabled during this time to communicate with other devices.

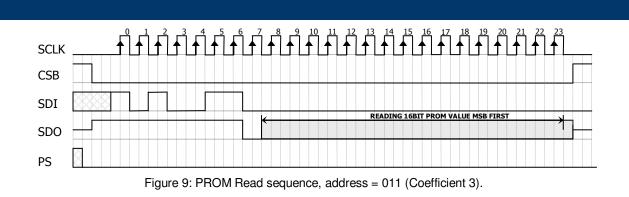
After the conversion, using ADC read command the result is clocked out with the MSB first. If the conversion is not executed before the ADC read command, or the ADC read command is repeated, it will give 0 as the output result. If the ADC read command is sent during conversion the result will be 0, the conversion will not stop and the final result will be wrong. Conversion sequence sent during the already started conversion process will yield incorrect result as well.



## Figure 8: ADC Read sequence

### PROM READ SEQUENCE

The read command for PROM shall be executed once after reset by the user to read the content of the calibration PROM and to calculate the calibration coefficients. There are in total 8 addresses resulting in a total memory of 128 bit. Address 0 contains factory data and the setup, addresses 1-6 calibration coefficients and address 7 contains the serial code and CRC. The command sequence is 8 bits long with a 16 bit result which is clocked with the MSB first.



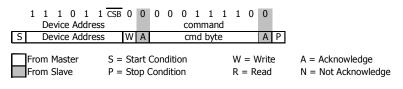
## I<sup>2</sup>C INTERFACE

### COMMANDS

Each  $I^2C$  communication message starts with the start condition and it is ended with the stop condition. The MS5611-01BA address is 111011Cx, where C is the complementary value of the pin CSB. Since the IC does not have a microcontroller inside, the commands for  $I^2C$  and SPI are quite similar.

### **RESET SEQUENCE**

The reset can be sent at any time. In the event that there is not a successful power on reset this may be caused by the SDA being blocked by the module in the acknowledge state. The only way to get the MS5611-01BA to function is to send several SCLKs followed by a reset sequence or to repeat power on reset.





### **PROM READ SEQUENCE**

The PROM Read command consists of two parts. First command sets up the system into PROM read mode. The second part gets the data from the system.

1 1 1 0 1 1 CSB Device Address S Device Address	0 0 1 0 1 0 0 1 command W A cmd byte	1 0 0							
From MasterS = Start ConditionW = WriteA = AcknowledgeFrom SlaveP = Stop ConditionR = ReadN = Not Acknowledge									
Figure 11: I <sup>2</sup> C Cor	mmand to read mer	nory address	= 011 (Coefficient	: 3)					
$1 1 1 0 1 1 \overline{CSE}$		X X X 0 X	X X X X X X X	0					
S Device Address	data R A Memory bit 1	.5 - 8 A	data Memory bit 7 - 0	NP					
	= Start Condition = Stop Condition	W = Write R = Read	A = Acknowledge N = Not Acknowled	ge					

Figure 12: I<sup>2</sup>C answer from MS5611-01BA

### **CONVERSION SEQUENCE**

A conversion can be started by sending the command to MS5611-01BA. When command is sent to the system it stays busy until conversion is done. When conversion is finished the data can be accessed by sending a Read command, when an acknowledge appears from the MS5611-01BA, 24 SCLK cycles may be sent to receive all result bits. Every 8 bit the system waits for an acknowledge signal.

1 1 0 1 CSB 0 0 1 0 0 1 0   Device Address command   S Device Address W A cmd byte	0 0 0 A P							
From Master S = Start Condition From Slave P = Stop Condition	W = WriteA = AcknowledgeR = ReadN = Not Acknowledge	lge						
Figure 13: I <sup>2</sup> C Command to initiate a press	Figure 13: I <sup>2</sup> C Command to initiate a pressure conversion (OSR=4096, typ=D1)							
1   1   0   1   1   CSB   0	0 0 0 A P							
From Master S = Start Condition From Slave P = Stop Condition	W = WriteA = AcknowledgeR = ReadN = Not Acknowledge	lge						
Figure 14: I <sup>2</sup> C ADC read sequence								
1 1 0 1 I CSB 1 0 X	data	XXXXX0 data ca7-0 NP						
From MasterS = Start ConditionW = WriteFrom SlaveP = Stop ConditionR = Read	A = Acknowledge N = Not Acknowledge							

Figure 15: I<sup>2</sup>C answer from MS5611-01BA

### CYCLIC REDUNDANCY CHECK (CRC)

MS5611-01BA contains a PROM memory with 128-Bit. A 4-bit CRC has been implemented to check the data validity in memory. The application note AN520 describes in detail CRC-4 code used.

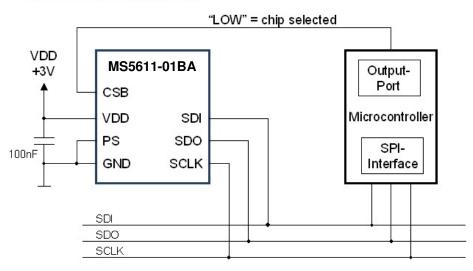
A d d	D B 1 5	D B 1 4	D B 1 3	D B 1 2	D B 1 1	D B 1 0	D B 9	D B 8	D B 7	D B 6	D B 5	D B 4	D B 3	D B 2	D B 1	D B 0
0	16 bit reserved for manufacturer															
1	Coefficient 1 (16 bit unsigned)															
2	Coefficient 2 (16 bit unsigned)															
3	Coefficient 3 (16 bit unsigned)															
4	Coefficient 4 (16 bit unsigned)															
5		Coefficient 5 (16 bit unsigned)														
6		Coefficient 6 (16 bit unsigned)														
7																

Figure 16: Memory PROM mapping

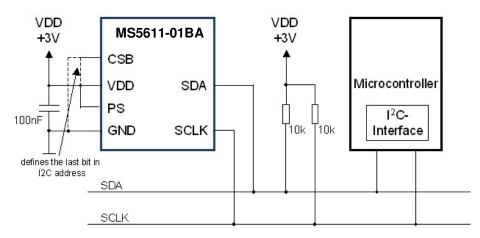
## **APPLICATION CIRCUIT**

The MS5611-01BA is a circuit that can be used in conjunction with a microcontroller in mobile altimeter applications. It is designed for low-voltage systems with a supply voltage of 3 V.

### SPI protocol communication



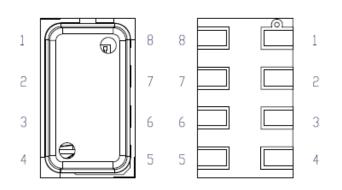
### I<sup>2</sup>C protocol communication



#### Figure 17: Typical application circuit with SPI / I<sup>2</sup>C protocol communication

## **PIN CONFIGURATION**

Pin	Name	Туре	Function
1	VDD	Р	Positive supply voltage
2	PS	I	Protocol select PS high (VDD) $\rightarrow$ I <sup>2</sup> C PS low (GND) $\rightarrow$ SPI
3	GND	G	Ground
4	CSB	CSB I	Chip select (active low),
5	COD	I	internal connection
6	SDO	0	Serial data output
7	SDI / SDA	I / IO	Serial data input / I <sup>2</sup> C data IO
8	SCLK	I	Serial data clock



## **DEVICE PACKAGE OUTLINE**

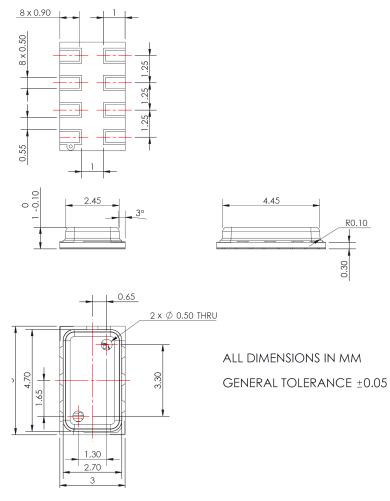
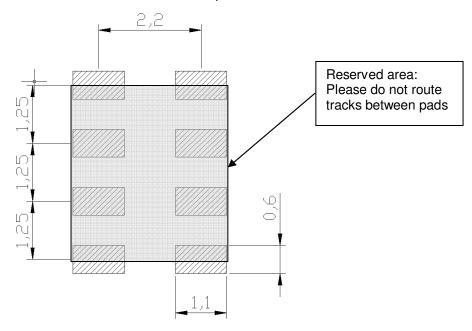


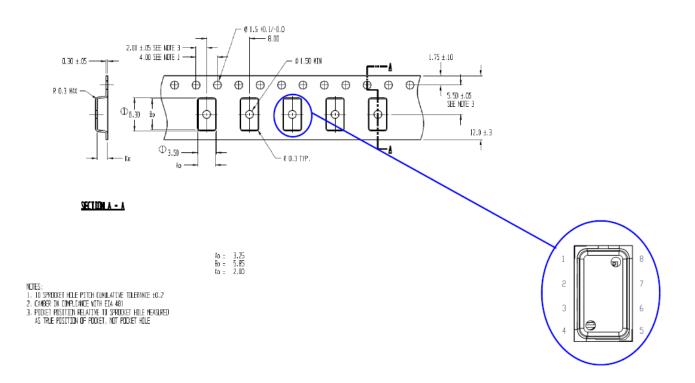
Figure 18: MS5611-01BA03 package outline

## **RECOMMENDED PAD LAYOUT**

Pad layout for bottom side of the MS5611-01BA soldered onto printed circuit board.



## SHIPPING PACKAGE



## MOUNTING AND ASSEMBLY CONSIDERATIONS

### SOLDERING

Please refer to the application note AN808 available on our website for all soldering issues.

### MOUNTING

The MS5611-01BA can be placed with automatic Pick & Place equipment using vacuum nozzles. It will not be damaged by the vacuum. Due to the low stress assembly the sensor does not show pressure hysteresis effects. It is important to solder all contact pads.

### CONNECTION TO PCB

The package outline of the module allows the use of a flexible PCB for interconnection. This can be important for applications in watches and other special devices.

### CLEANING

The MS5611-01BA has been manufactured under cleanroom conditions. It is therefore recommended to assemble the sensor under class 10'000 or better conditions. Should this not be possible, it is recommended to protect the sensor opening during assembly from entering particles and dust. To avoid cleaning of the PCB, solder paste of type "no-clean" shall be used. Cleaning might damage the sensor!

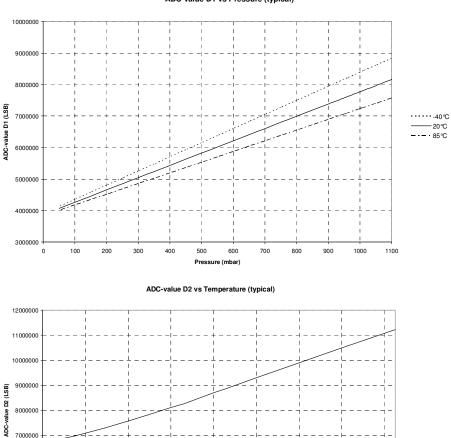
### ESD PRECAUTIONS

The electrical contact pads are protected against ESD up to 4 kV HBM (human body model). It is therefore essential to ground machines and personnel properly during assembly and handling of the device. The MS5611-01BA is shipped in antistatic transport boxes. Any test adapters or production transport boxes used during the assembly of the sensor shall be of an equivalent antistatic material.

### DECOUPLING CAPACITOR

Particular care must be taken when connecting the device to the power supply. A 100 nF ceramic capacitor must be placed as close as possible to the MS5611-01BA VDD pin. This capacitor will stabilize the power supply during data conversion and thus, provide the highest possible accuracy.

## **TYPICAL PERFORMANCE CHARACTERISTICS**



#### ADC-value D1 vs Pressure (typical)

Guangzhou Ankai Electronic Instrument Co., Ltd.

-40

-20

0

20

40

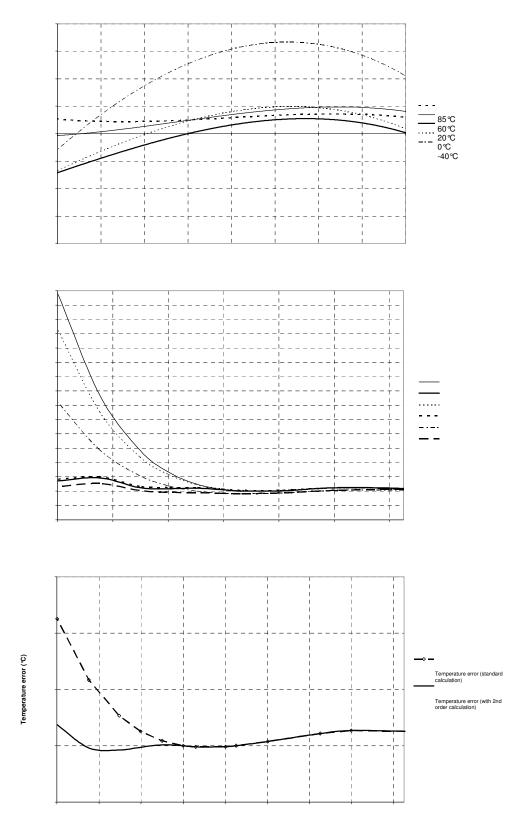
Temperature (°C)

60

80

100

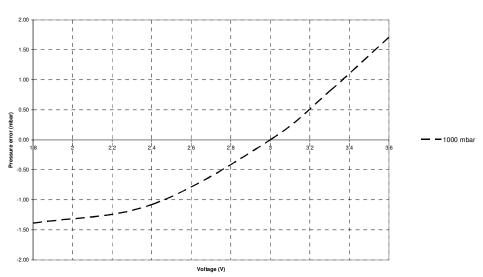
120



## TYPICAL PERFORMANCE CHARACTERISTICS (CONTINUED)

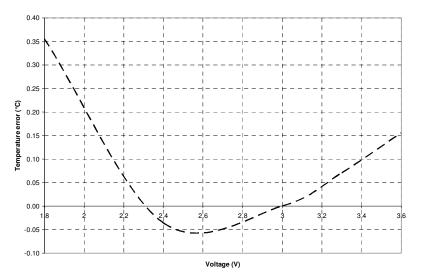
Guangzhou Ankai Electronic Instrument Co., Ltd.

## **TYPICAL PERFORMANCE CHARACTERISTICS (CONTINUED)**



#### Pressure error vs supply voltage (typical)

Temperature error vs supply voltage (typical)



## **ORDERING INFORMATION**

Product Code	Product	Art. No
MS5611-01BA03	Variometer Module Thin Metal Cap	MS561101BA03-50